EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	4112	((mobile adj robot) or (robot near3 bipedal))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 20:10
L2	237	1 and (floor near3 react$6)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 20:11
L3	128	2 and (gait or path$3) and model	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 20:12
L4	110	3 and (boundary or limit$7)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 20:13
L5	2	4 and ((second or third) near3 model) and (correct&7 or error or compar$7) and (gait with (desir$3 or predeterm7))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 20:20
L6	17	2 and ((second or third) near3 model) and (correct&7 or error or compar$7) and ((gait or step or stride) with (desir$3 or predeterm$6 or target$3))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 20:50
L7	12	6 and ((restrict/$6 or limit$6) with force)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 20:53
L8	12	7 and (predeterm$5 with (time or period))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 20:55
L9	11	8 and (predeterm$6 near3 (deviat$6 or error))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 20:59
L10	1	9 and (m adj6 model) and (n adj6 model)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 21:08
L11	10	9 not 10	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 21:02

L12	5	11 and (first adj3 model) and (second adj3 model)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 21:07
L13	5	12 and (gait near3 (adjust$6 or chang$3 or correct$6))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 21:09
L14	1	12 and (gait near3 (adjust$6 or chang$3 or correct$6)).clm.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 21:12
L15	4	13 and ((model near3 parameter) with (gait near3 parameter))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 21:14
L16	136	700/252.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 21:13
L17	1635	701/23.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 21:14
L18	706	901/1.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 21:14
L19	828	318/568.12.ccls.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 21:14
L20	2912	(16 or 17 or 18 or 19)	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 21:14
L21	2	20 and (robot near3 (bipedal or mobile)) and (gait or step) and (floor near3 force) and (boundary or limit$6) and ((model near3 parameter) with (gait near3 parameter))	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 21:22
L22	0	20 and (robot near3 (bipedal or mobile)) and (gait or step) and (floor near3 force) and (boundary or limit$6) and ((model near3 parameter) with (gait near3 parameter)) and ((generat$3 near3 generat$6) with (desir$3 or target$3 or predeterm$5)).clm.	US-PGPUB; USPAT; EPO; JPO; DERWENT	OR	ON	2007/09/30 21:25